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Computer Vision

Introduction

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DAIS, Ca' Foscari University of Venice

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About this course

Official UNIVE course page:

<http://www.unive.it/data/course/218005>

Unofficial course page:

http://www.dais.unive.it/~bergamasco/computer_vision.html

- 30 hours frontal lessons (lab included)
- Timetable: Monday and Tuesday 12:15 - 1:45 pm
- Code: CM0193



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About this course

Referral texts:

- R. C. Gonzalez e R.E. Woods. **Digital Image Processing** (3rd edition). Prentice Hall
- R. Szeliski. **Computer Vision Algorithms and Applications**. Springer

Additional useful readings:

- D. Forsyth and J. Ponce. **Computer Vision. A Modern Approach**. Prentice-Hall, 2002
- E. Trucco and A. Verri. **Introductory Techniques for 3D Computer Vision**. Prentice-Hall, 1998



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About the teacher



Filippo Bergamasco

http://www.dais.unive.it/~bergamasco/computer_vision.html

- I'm currently a postdoctoral research fellow here at DAIS
- KiiS research group. I work on 3D reconstruction, camera calibration, ego-motion estimation, photogrammetry etc.



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About the teacher



Filippo Bergamasco

http://www.dais.unive.it/~bergamasco/computer_vision.html

For any question regarding this course, please contact me via mail: filippo.bergamasco@unive.it

Or come visit me at my office



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About the exam...

Final exam consists in the development of a project to be performed individually.

Project submission information: (more will follow)

- Send me the full source-code and data at least 1 week before the exam
- During the exam, I'll ask you to show me your project and explain its details (choice made, trade-offs, strengths and limitations)
- The goal is to evaluate your knowledge of the most common computer vision techniques and theories



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About the exam...

This year project will be about the development of a simple augmented-reality system

Requirements:

- The project must be developed in C++ and can use the OpenCV Computer Vision Library
- I'm not particularly interested in the coding style, but a clean object-oriented organization of the code is considered a plus
- Laboratory lessons are designed to let you develop useful core parts for your project (so use the lab time wisely!)



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About the exam...

This year project will be about the development of a simple augmented-reality system

DEMO TIME!



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Are you interested in a challenging computer vision thesis?



WE WANT YOU!

A thesis activity can substitute the proposed project and assignments.

If interested, contact me as soon as possible so we can discuss the details together.



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About the lab

We will spend some hours in the lab so you can put your hands on some of the algorithms discussed during the course

After each lab session you will be asked to complete an assignment within 2 weeks (deadline can be slightly postponed in exceptional cases)

Completing all the assignments is required (not sufficient) to obtain the full-marks (lode)



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What is Computer Vision?

Computer vision is about building an automatic system that “sees”

- Difficult to give a concise definition since the area spans multiple different problems (we will see some examples in a minute...)

How we'll consider cv in this course:

*“A set of computational techniques aiming at estimating or making explicit the **geometric and dynamic properties** of the **3D world** from **digital images**”*

Introductory techniques for 3D computer vision - E. Trucco, A. Verri



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What is Computer Vision?

Different levels of vision:

1. Low (Image processing)

- a. Image restoration
- b. Contrast enhancement
- c. Noise reduction

Image \longrightarrow Image

2. Medium

- a. Segmentation
- b. Shape recognition

Images \longrightarrow attributes/features

3. High

- a. Scene understanding

Images \longrightarrow concepts



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What is Computer Vision?

The purpose of a machine vision system is to produce a symbolic description of what is being imaged

As human, we perceive the three-dimensional structure of the world around us with apparent ease



Easy to distinguish the flower in the foreground from the leaves in the background

From a signal point of view, there are just variations in color and brightness



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What is Computer Vision?



What we see

0	3	2	5	4	7	6	9	8
3	0	1	2	3	4	5	6	7
2	1	0	3	2	5	4	7	6
5	2	3	0	1	2	3	4	5
4	3	2	1	0	3	2	5	4
7	4	5	2	3	0	1	2	3
6	5	4	3	2	1	0	3	2
9	6	7	4	5	2	3	0	1
8	7	6	5	4	3	2	1	0

What a computer sees



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A difficult business

Despite the remarkable advances in the last decades...

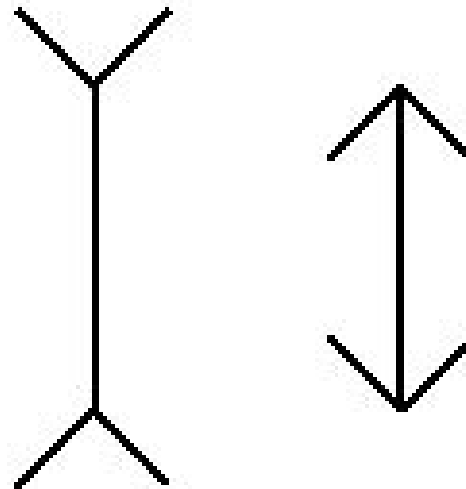
“the dream of having a computer interpret an image at the same level as a two-year old (for example, counting all of the animals in a picture) remains elusive”

Humans and animals can interpret images so effortlessly while computer vision algorithms are still error prone:

- **Perceptual** components of artificial intelligence (such as vision) is probably as difficult as **cognitive** ones (logic proving, planning)

Human vision

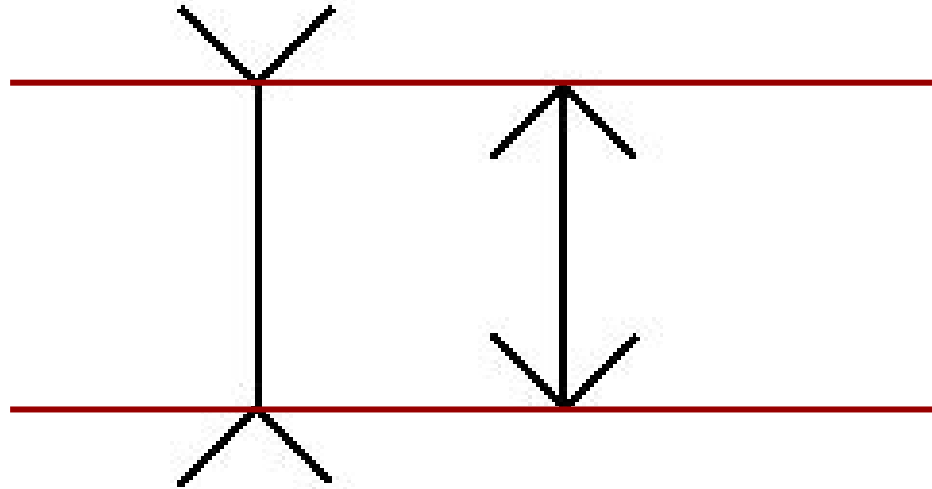
Optical illusions give us interesting clues of how the human visual system works (and the inherent assumptions made by our brain)



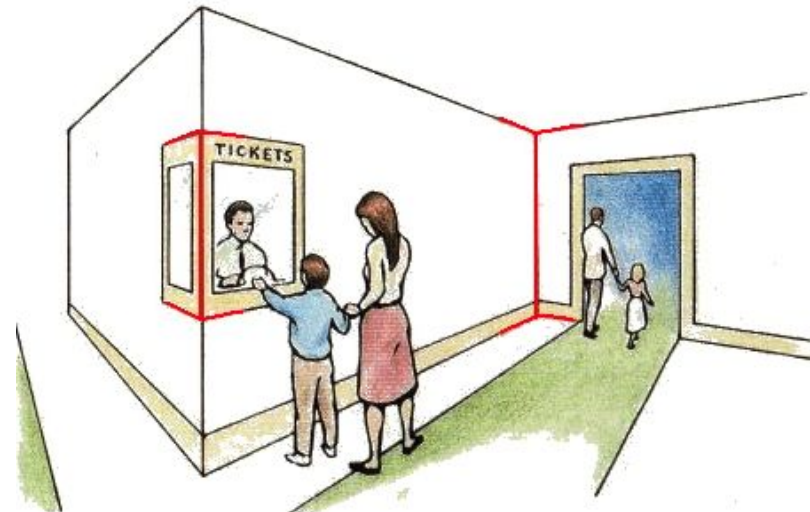
Which one is longer?

Müller-Lyer Illusion

Human vision



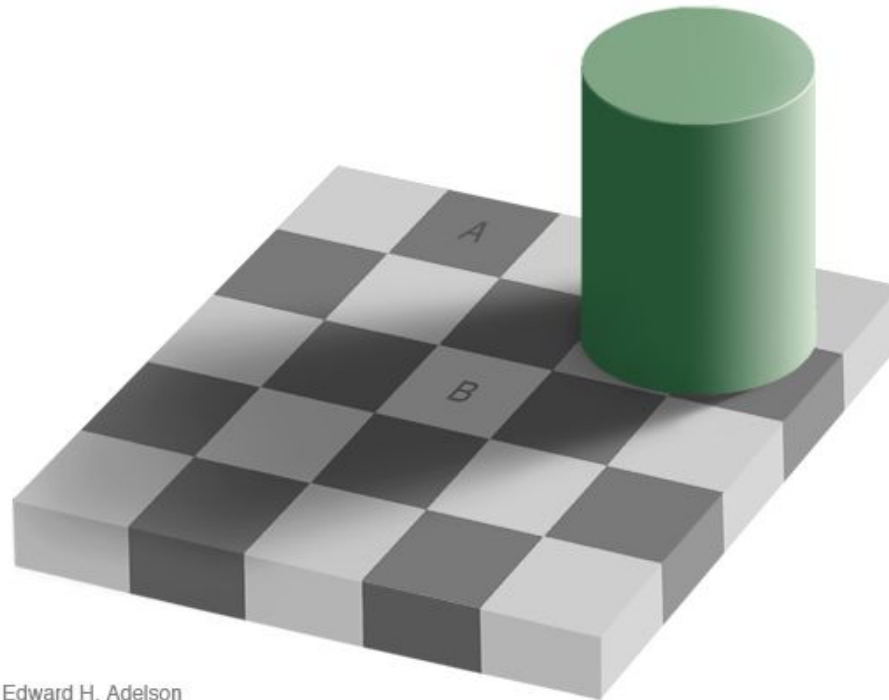
The Müller-Lyer illusion occurs because the visual system processes that judge depth and distance assume in general that the "angles in" configuration corresponds to an object which is closer, and the "angles out" configuration corresponds to an object which is far away.





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Human vision



Edward H. Adelson

Which one is
brighter?

The percept is due to brightness constancy, the visual system's attempt to discount illumination when interpreting colors



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Human vision

Rotating mask illusion



When determining the shape of an object only from shading (with no stereo vision), the brain assumes a convex shape (especially for faces)



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Human vision

Optical Perception





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Why is difficult?

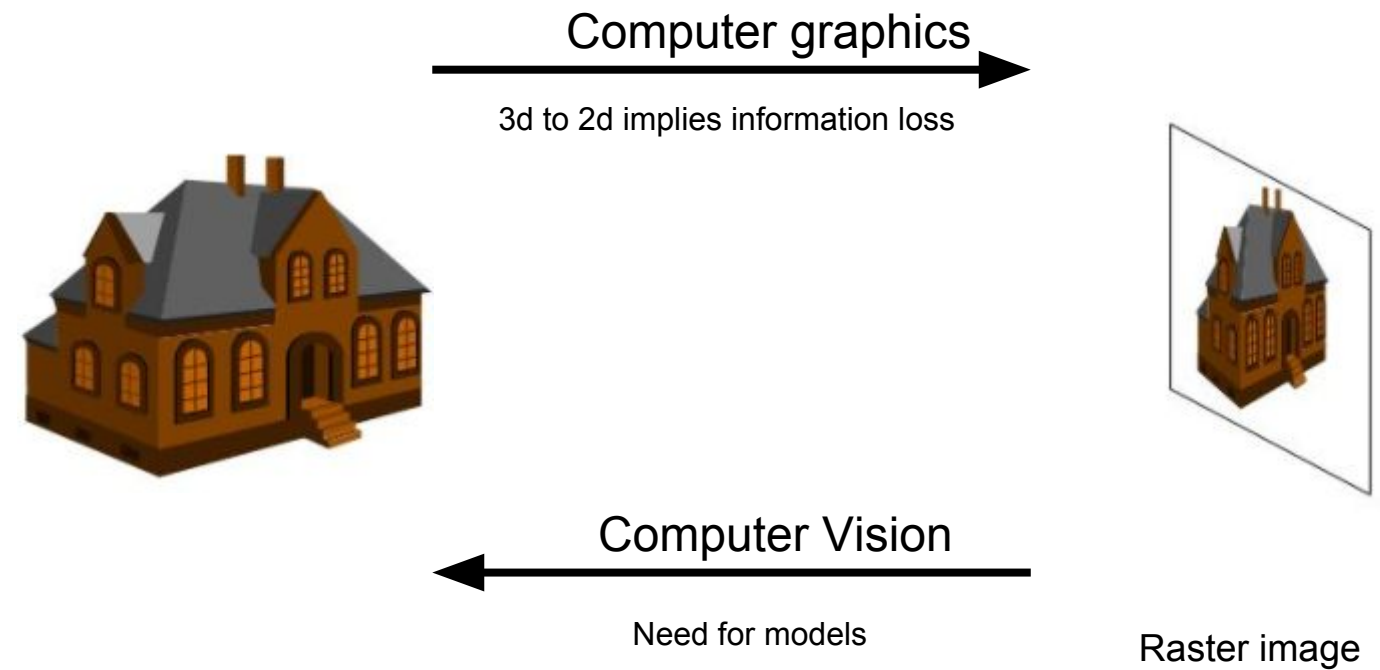
Giving a symbolic description of the contents of an image is difficult because is intrinsically an **inverse problem**:

- We want to recover some unknowns given insufficient information to fully specify the solution
- We must resort to physic-based and/or probabilistic-based models to **disambiguate potential solutions**



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Computer Vision vs. Graphics



- A house
- Some polygons
- Lines, edges



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Computer Vision vs. Graphics

The **models** we use in computer vision are usually developed by:

- Physics: radiometry, optics, etc.
- Computer graphics

And describe how:

- Objects move or animate
- Light reflects from object surfaces
- Shapes get projected to the sensor image plane
- etc.



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Computer Vision vs. Graphics

In limited contexts, computer graphics nowadays is so advanced that the illusion of reality is almost perfect





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Computer Vision applications

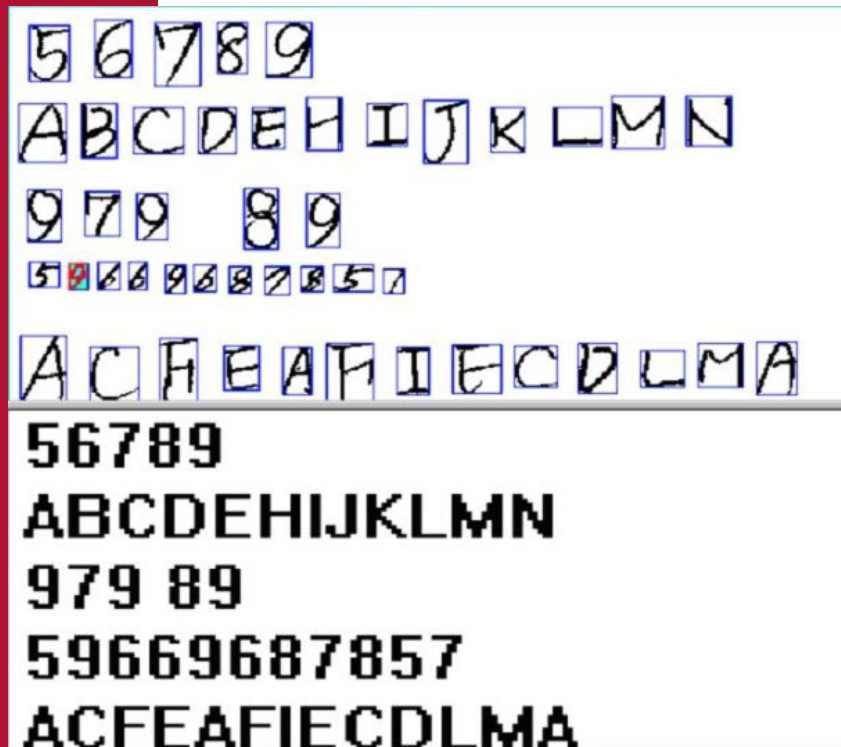
So, what are the most common applications in which computer vision is used today?



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Computer Vision applications

Optical Character Recognition (OCR)





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Computer Vision applications

Optical Character Recognition (OCR)

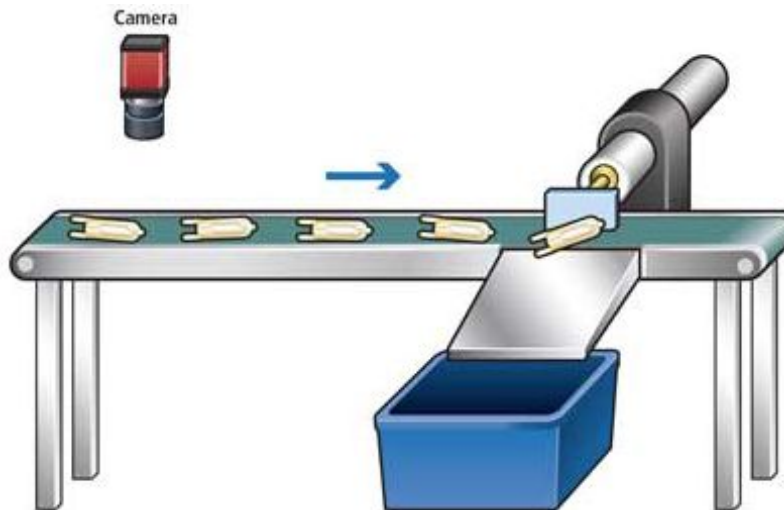




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Computer Vision applications

Machine inspection

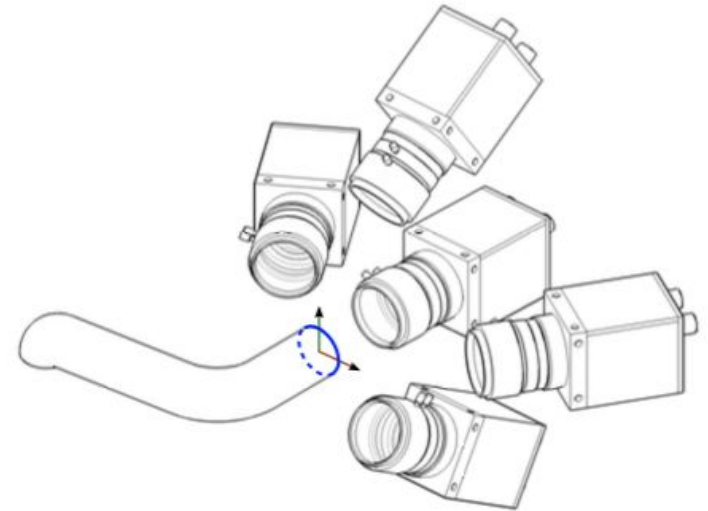
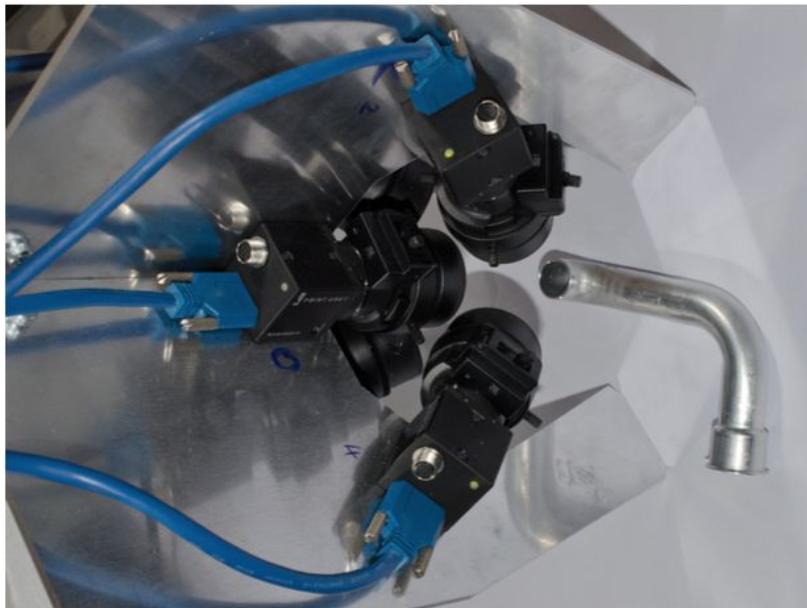




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Computer Vision applications

Machine inspection



Pipe inspection device developed in our lab

Computer Vision applications

Surveillance

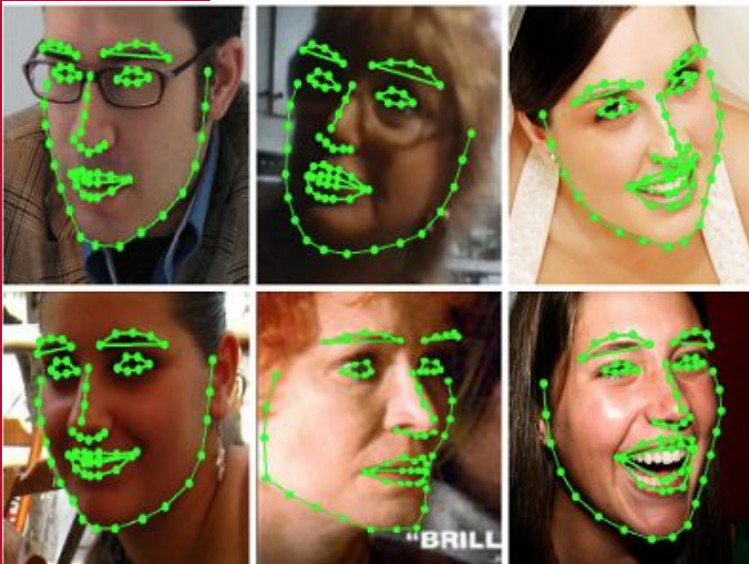




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Computer Vision applications

Face detection and recognition

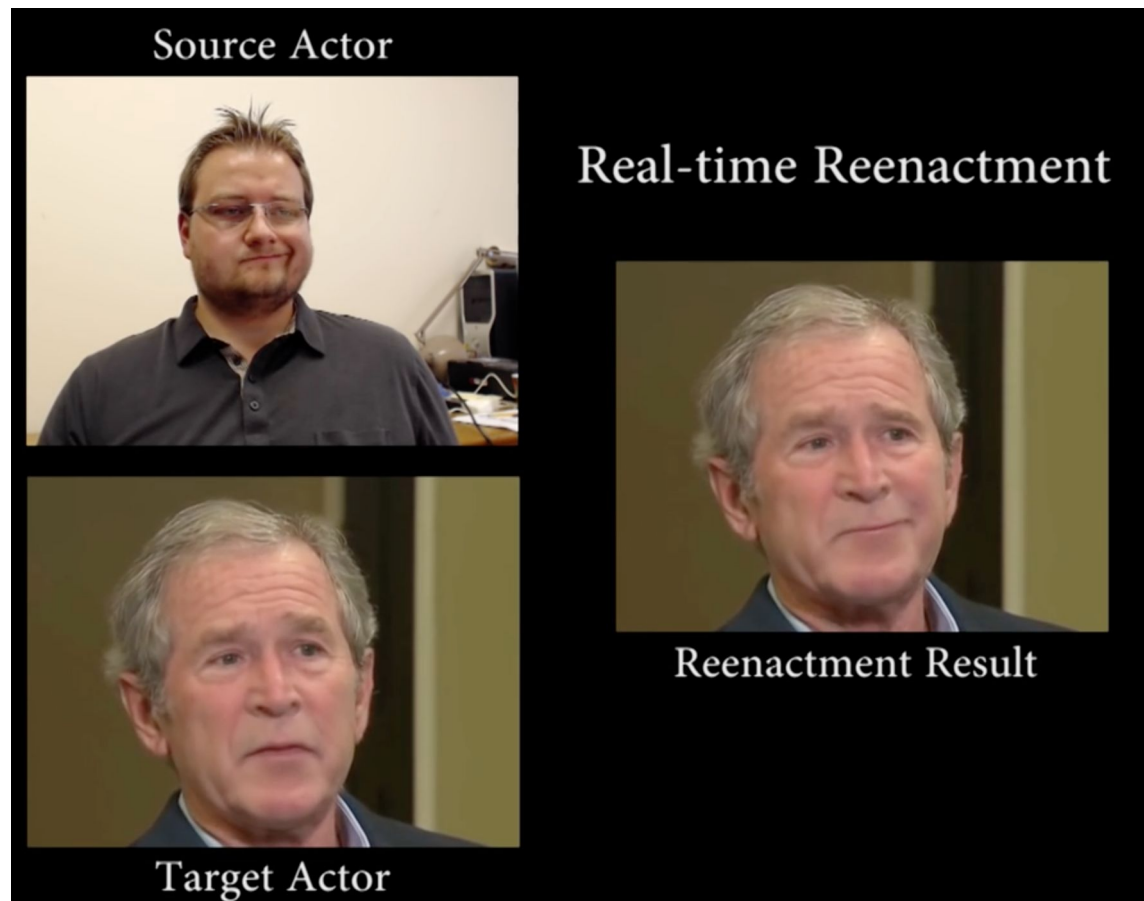




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Face capture and reenactment

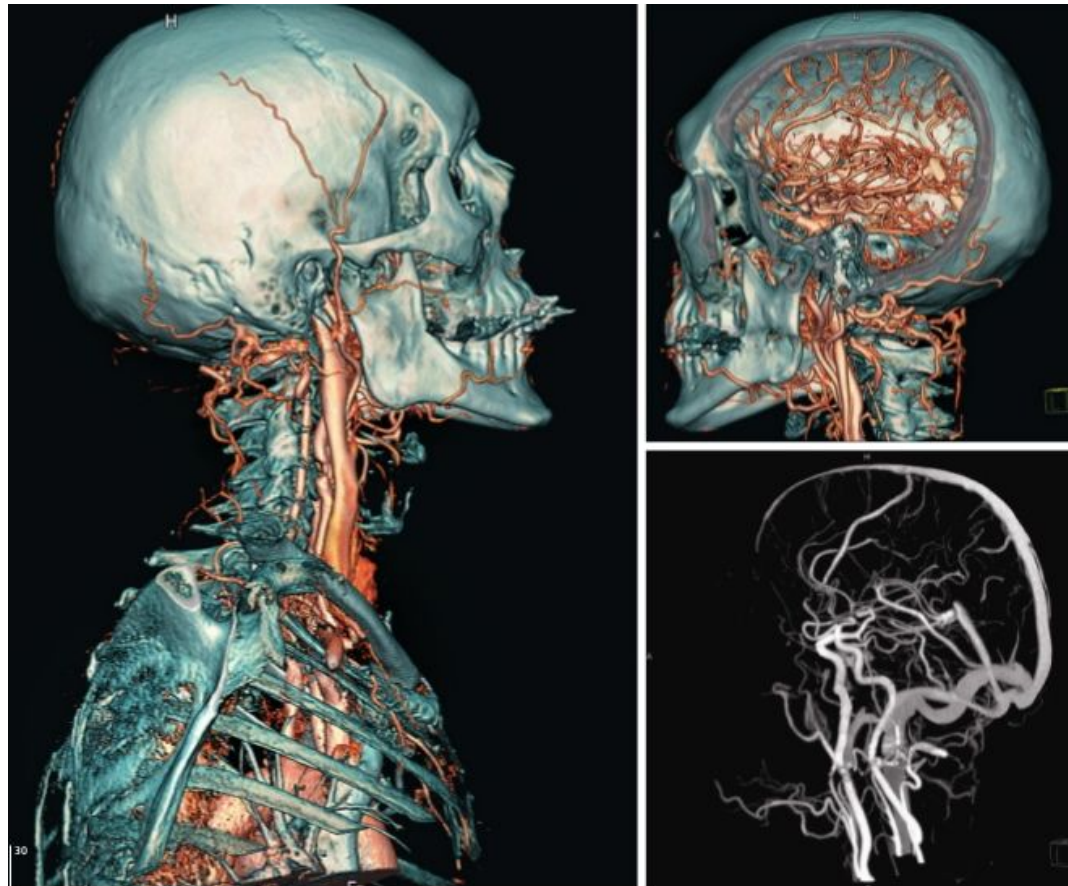




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Computer Vision applications

Medical image analysis





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Computer Vision applications

Driving assistance





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Computer Vision applications

Driving autopilot (autonomous vehicles)





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Computer Vision applications

Smart advertising

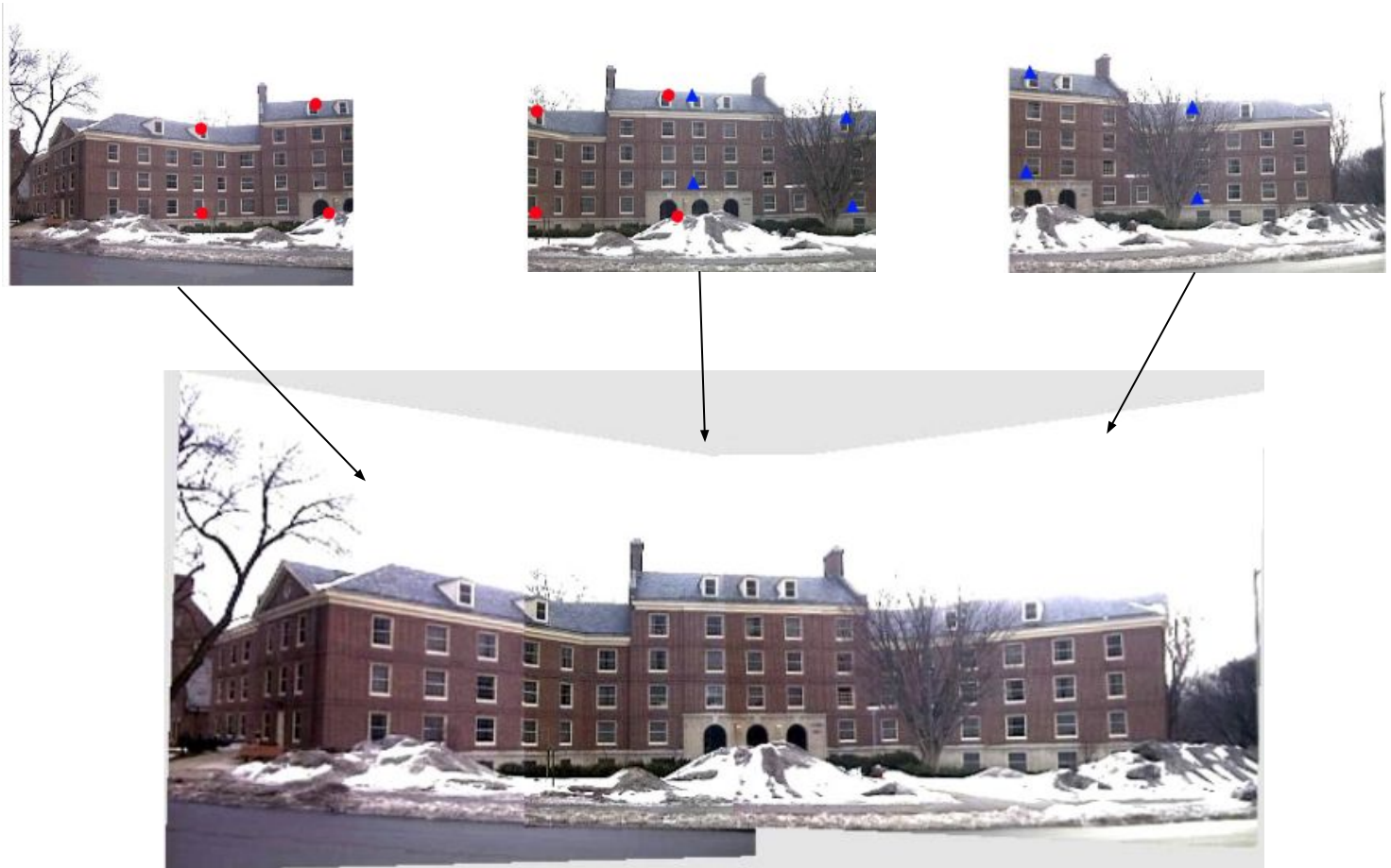




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Computer Vision applications

Panorama stitching

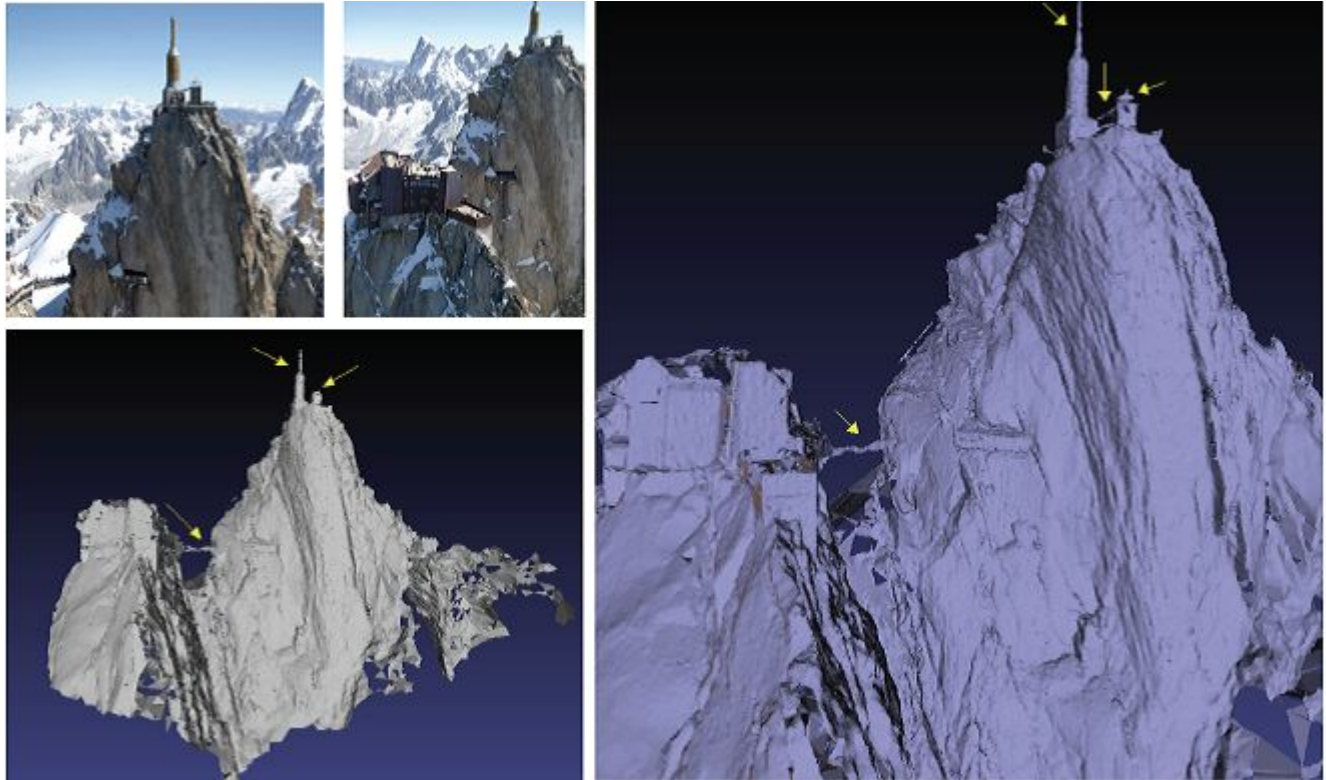




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Computer Vision applications

Stereo 3D reconstruction

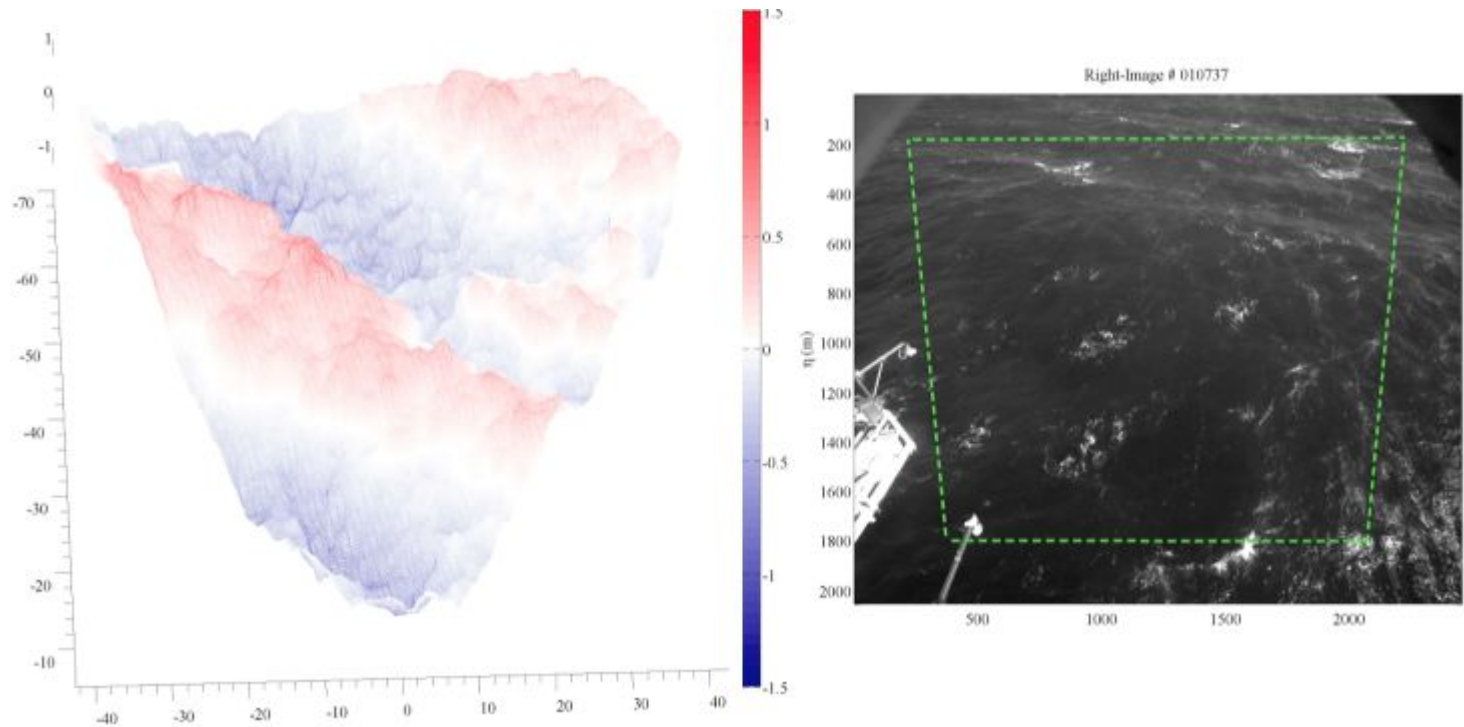




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Computer Vision applications

Stereo 3D reconstruction



Sea waves 3D reconstruction pipeline

<http://www.dais.unive.it/wass>



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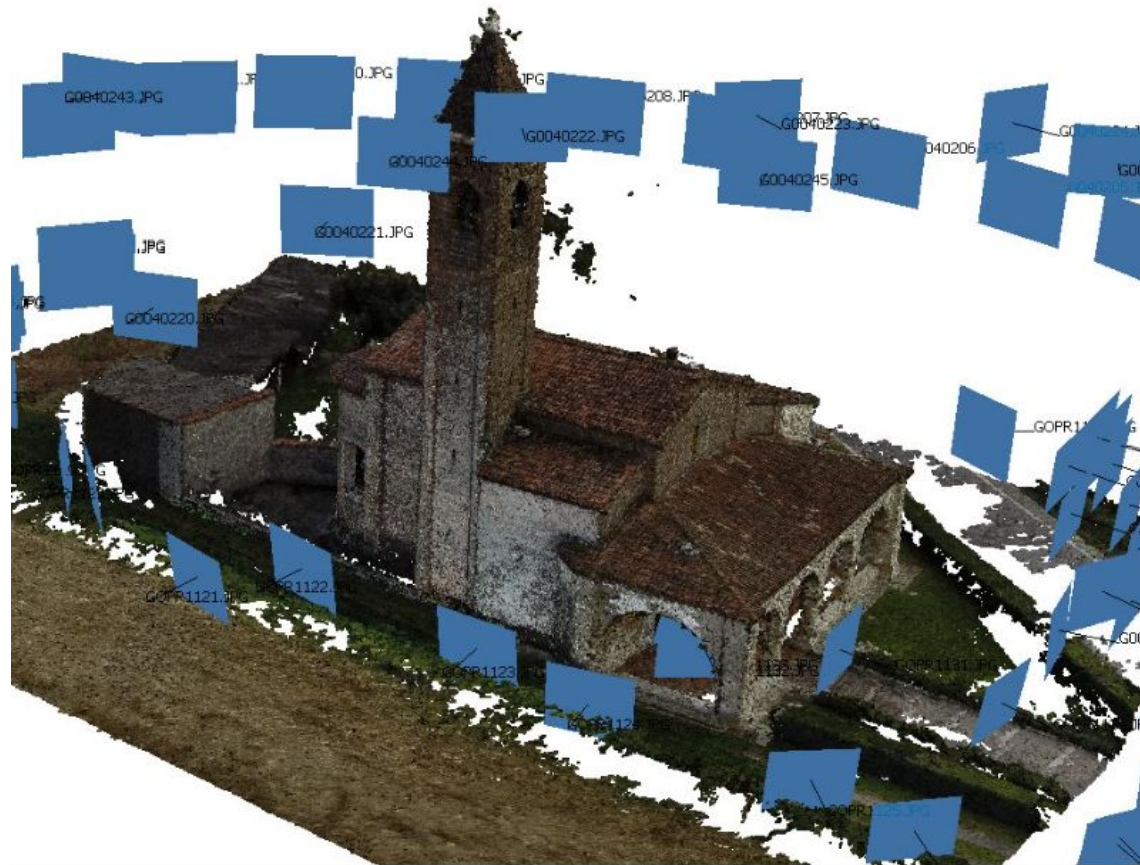
Computer Vision applications

3D reconstruction (structure from motion)



Computer Vision applications

3D reconstruction (structure from motion)

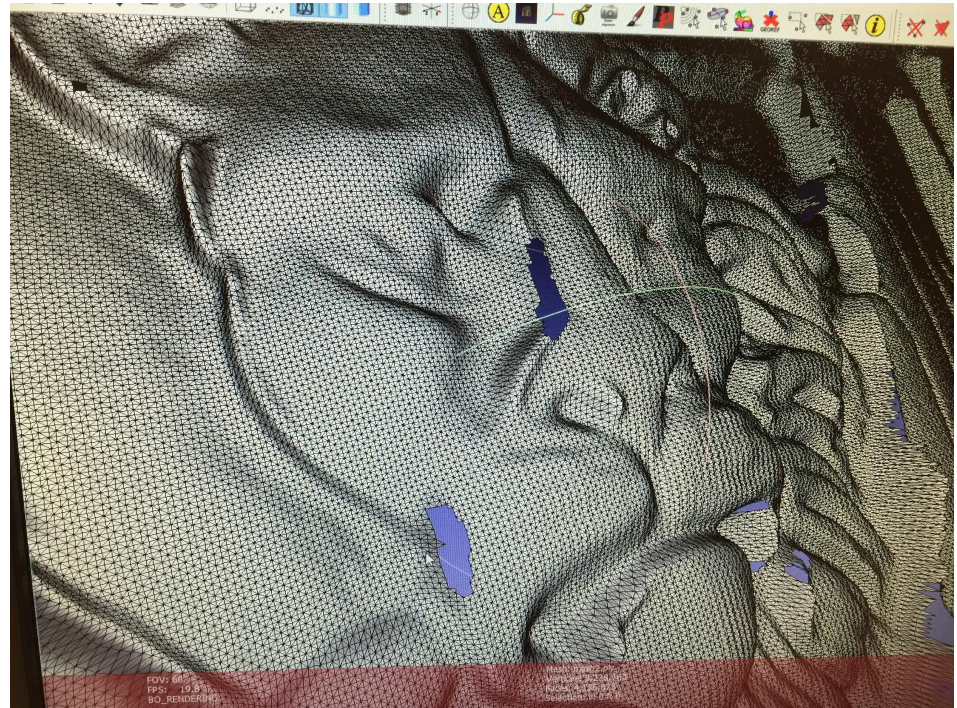
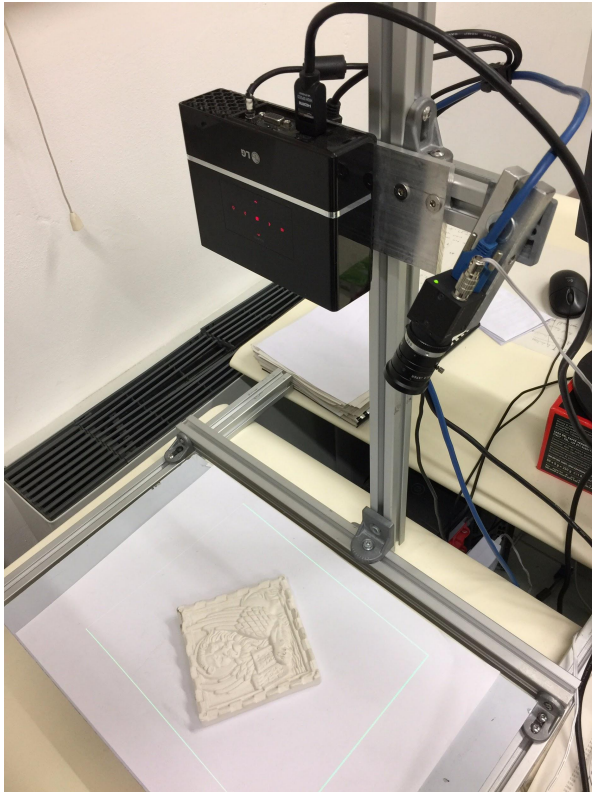




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Computer Vision applications

Structured-light scanning





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Computer Vision applications

And much, much more...





1970

Digital image processing
Blocks world, line labeling
Generalized cylinders
Pictorial structures
Stereo correspondence
Intrinsic images
Optical flow
Structure from motion
Image pyramids
Scale-space processing
Shape from shading, texture, and focus
Physically-based modeling
Regularization
Markov Random Fields
Kalman filters
3D range data processing
Projective invariants
Factorization
Physics-based vision
Graph cuts
Particle filtering
Energy-based segmentation
Face recognition and detection
Subspace methods
Image-based modeling and rendering
Texture synthesis and inpainting
Computational photography
Feature-based recognition
MRF inference algorithms
Category recognition
Learning

1980

1990

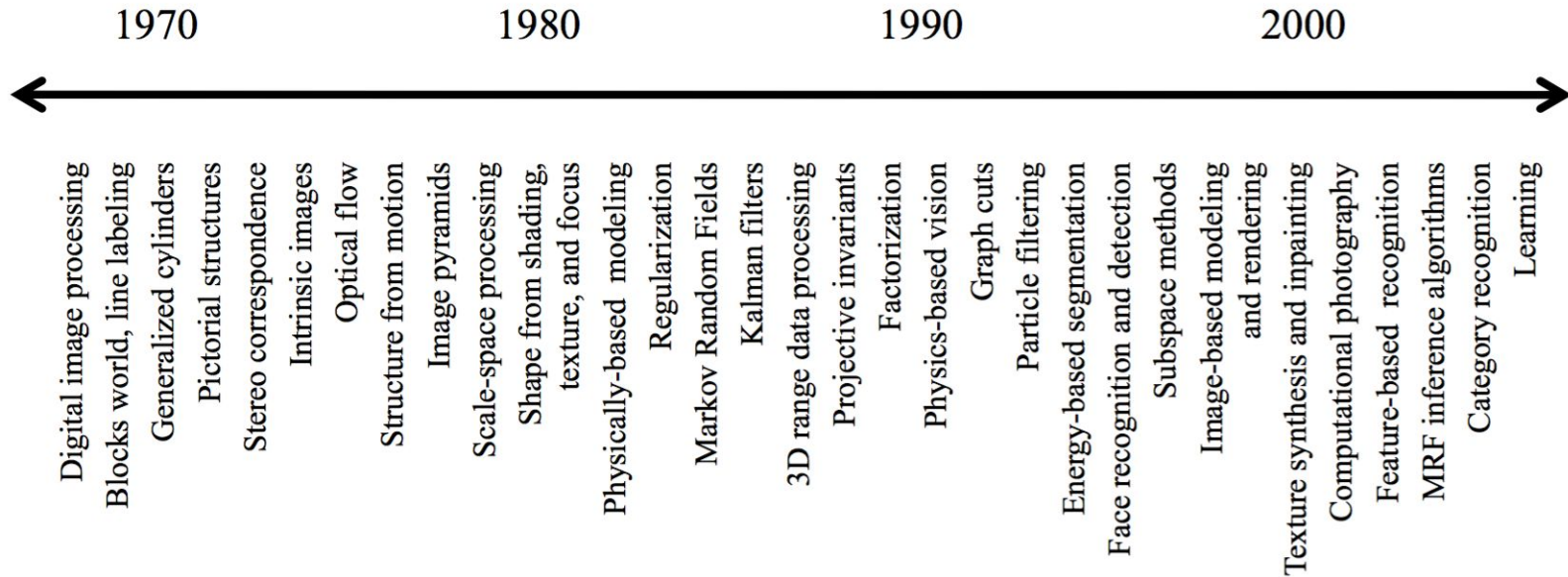
2000

Lines extraction and labelling, stereo correspondences, optical flow, structure from motion



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A Brief History



1980: attention was focused on more sophisticated mathematical techniques for performing quantitative image and scene analysis:

Variational optimization, MRFs, Image Pyramids, 3D scanning



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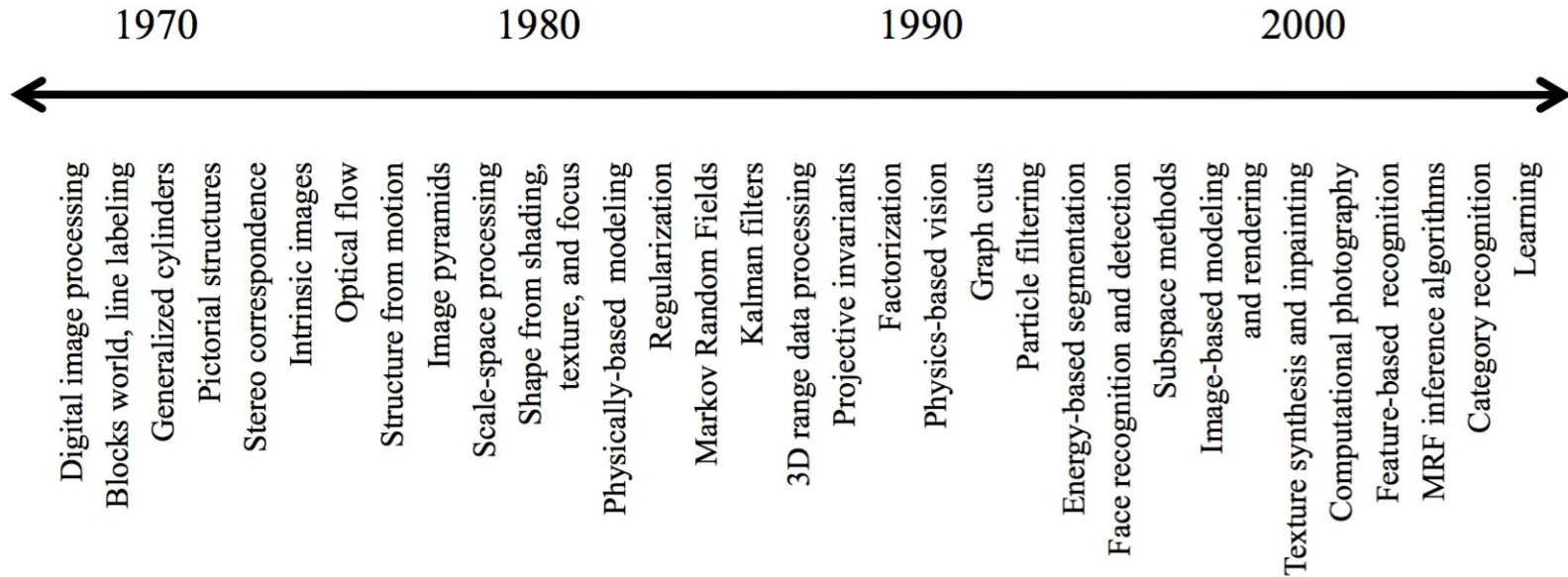
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A Brief History



2000: Continuous advances of all the previous topics:

SIFT features, texture synthesis, computational photography, learning