

# A basic tool for the modeling of Marked-Controlled Reconfigurable Petri Nets\*

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In [1, 4], we introduced the model of *net rewriting systems* (NRS) and a subclass of this model, *reconfigurable nets* (RN), to analyze, simulate and verify concurrent and distributed systems that are subject to structural dynamic changes. Both models arise from two different lines of research that were conducted in the field of the Petri net formalism [6]. The first line covers various proposals for merging Petri nets with *graph grammars* [2, 3, 7], while the second line, which is best represented by *Valk's self-modifying nets* [8], considers Petri nets whose flow relations can vary at runtime. *Reconfigurable nets* attempt to combine the most relevant aspects of both of these approaches and constitute a class of models for which each of the fundamental properties of Petri nets (place boundedness, reachability, deadlock and liveness) are decidable. The translation of this model into Petri nets is automatic [4]. This equivalence ensures that the model is amenable to automatic verification tools. In contrast, the class of *net rewriting systems* is Turing powerful [4]. In [5], we introduced *marked-controlled net rewriting systems* (MCNRS) and *marked-controlled reconfigurable nets* (MCRN) as an extension of net rewriting systems and reconfigurable nets, respectively, where the enabling of a rewriting rule not only depends on the net topology, but also depends on the net marking according to some net places named control places. In MCNRS, a system configuration is described as a Petri net, and a change in configuration is described as a graph rewriting rule, which consists of replacing part of the system (the part that matches the left-hand side of the rewriting rule) with another one (given by the right-hand side of the rewriting rule). A MCRN is a MCNRS where a change in configuration is limited to the modification of the flow relations of the places in the domain of the rewriting rule involved; i.e., the set of places and transitions is left unchanged by rewriting rules.

In this work, we introduce a basic tool to analyze the structure and dynamic behavior of systems that are modeled using our nets in order to evaluate them and suggest improvements or changes. The goal of our MCRNet tool is to analyze, simulate, and verify real systems that are modeled by MCRN. On the basis of the equivalence between Petri nets and MCRN [5], we have initially

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opted to develop a tool that exploits the capabilities of the Petri net tools that are currently available [9]. The main goal of our tool is the implementation of a translation algorithm of a MCRN into an equivalent Petri net. We have chosen PIPE as the graphical editor, simulator and analyzer. PIPE is an open source, platform independent tool for Petri nets developed at the Imperial College of Science Technology and Medicine in the University of London. The last version of PIPE can be obtained at [sourceforge.net/projects/pipe2/](http://sourceforge.net/projects/pipe2/). MCRNet integrates PIPE with the translator. Therefore, the user can draw the initial state and rewriting rules of the MCRN, which is then translated into its equivalent Petri net. In addition, a simulation and an analysis of this net can be performed. All these processes are integrated in the MCRNet tool. MCRNet can be obtained by sending an email to the author ([mlllorens@dsic.upv.es](mailto:mlllorens@dsic.upv.es)). We are now working on the implementation of an algorithm that obtains the state of a MCRN from the corresponding Petri Net. The idea is that users can animate the Petri net (firings of enabled transitions) and, at any time, they can find and see the equivalent state of the equivalent MCRN. As further work, we will develop a tool that is completely autonomous. Our new tool will be able to directly carry out the editing, simulation and analysis of net properties on MCRN. We are currently working on the theoretical aspects of the analysis methods for Petri nets in order to apply them directly to MCRN.

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